

Predictive Wear Model

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Motivation: Computer-Aided Design/Optimization of Wear-Resistant Surfaces

There are more then 100 wear laws in the literature. This is no surprise as wear can be the result of several different mechanisms acting in combination like:

adhesive wear

- abrasive wear
- fatigue
- fretting wear
- . erosive wear

However, in order to achieve the objective of an Computer-Aided Design of Multi-Scale Surface Structures as proposed in 2010 (see Fig. 1) one has to account for the complex nature of wear by introducing a general wear law. Such an approach would facilitate an application-tailored design or optimization of arbitrarily structured surfaces by means of model-based simulations



saving a lot of money for scarce raw materials and time for time-consuming trial-and-error testing (Fig. 2).



Yet Another Wear Law? No, a General Approach.

All the many types of wear can be incorporated into a single tribology law by extracting decomposition limits from first principle approaches [3-4] and comparing them to the contact fields of the complex multi-physics multi-body model describing the tribological effect. In the most simple case, any tribological process can be generalized as (c.f. [5-6]):

 $tribo-effect_{ij} = \hat{k}^{\sigma}_{ijkl} \,\sigma^{kl} + \hat{k}^{\varepsilon}_{ijkl} \,\varepsilon^{kl} + \hat{k}^{u}_{ijkl} \,u^{k}u^{l} + \sum_{i}^{N} \hat{k}^{S_{n}} \delta_{ij} S_{n}$

Luckily, in most cases it is sufficient to consider only the stresses of the tribological contact, yielding:

$$ribo - effect_{ij} \equiv w_{ij} = \hat{k}_{ijkl} \ \sigma^{kl} \equiv \delta_{ij} \left(k_{dvM} \frac{\sigma_{vM}}{Y(T)} \cdot e^{-\lambda_k \vec{r} \cdot \vec{r}} \right)$$

However, in order to not only properly calculate the contact fields of tribo experiments or applications but also correctly determine the wear moduli k_{iikl} one has to overcome some obstacles:

- mechanical characterization strictly physical
- quasi-static experiments \rightarrow dynamic contacts
 - friction \rightarrow temperature fields
 - phonons, shock waves
- . time-dependent material behavior
- non-linearity
- inhomogeneity (not only due to layered structure)

 from mechanical properties to wear performance Tools from absolutely different fields of physics will be necessary to overcome these obstacles.





Obstacle #3: Time-Dependency Classic standard linear solid for individual interactions: $E(t) = E_0 + E_1 e^{\overline{\tau(T_j(r,z),\mu)}}$ Resulting phenomenological $E(t) = E_0 + E_1 e^{\frac{-t}{r(T_j(r,t),\mu)}} + \vec{r} \cdot E_1 e^{\frac{-t}{r(T_j(r,t),\mu)}} \frac{t}{r^2} \frac{d\tau}{d\vec{r}}$ time-dependent E:

 $4 E_0 + E_1 e^{r(T_1(r,x),p)},$

If m>2:

 $F=C\cdot ig(h-h_0ig)^m$

Sharper then real effective indent indenter! shape $E(t) = E_0 + E_1 e^{-\frac{t}{\tau}}$ $F = C(t) \cdot \left(h - h_0(t)\right)^{m(t)}$ $F = 2 \cdot \left(\frac{1 - \nu_i^2}{E_i} + \frac{1 - \nu_s^2}{E_{s0} + E_{s1} \cdot e^{-\frac{1}{\tau}}}\right)^{-1} \cdot \left[\frac{n}{n+1}\right] \cdot \left(\frac{1}{D^{tot}} \cdot \left[1 - \varepsilon(n) \cdot \frac{n}{n+1}\right]\right)^{\frac{1}{n}}$

According to [7], this method is the only reliable and stable found in literature which also yields reproducible results.

Results: Physical-Tribological Parameters + Model-Based Wear Predictions

[6]

[8]





Evolution of wear depth and of von-Mises-stress profile as simulated for an erosive wear experiment after 0, 20, 70

Evolution of wear depth predicted by different models vs. experiment of a nano-fretting experiment (c.f. [8]).

References

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